# Stryke Force Team 2767 Talon SRX Motor training course Dec 2017 Presented by Jerry Culp, systems mentor

#### Chapter 1, Motors - 46 min

**Motor Physics and Construction** 

Motor Model and Schematic

Motor Speed Torque Curve

Motor Performance – Power and Efficiency

Motors in FIRST - Choices and Tradeoffs

Gearboxes – Getting the right speed and torque

**Motor Heat** 

Motor Drive – What is Pulse Width Modulation (PWM)

#### Chapter 2, Talon SRX - 52 min

Connecting to a Talon SRX

Communicating with a Talon SRX

Talon blink codes

Talon versions and firmware

Talon control modes

Talon Velocity mode

**Talon Parameters** 

#### Chapter 3, Talon Encoders and Sensors – 17 min

**Quadrature Encoders** 

**Analog Encoders** 

Sentinel Interface Board

#### Chapter 4, Control Loops – 49 min

Open Loop control

Closed Loop control

PID control

What is P – Proportional

P only live demo – Walk the line

PI – add the Integrator

PID – add a differentiator

PID + F – add Feed Forward

#### Chapter 5, Live Tuning Examples part 1 – 51 min

Stryke Force tuning tools

Tuning a no load CIM

Checking the axis open loop – confirm you understand your physical plant

Close the loop

Tuning F

Tuning P

# Chapter 6, Live Tuning Examples part 2 – 55 min

Tuning I

Tuning I zone

Tuning D

Talon Velocity Filters and other high-performance tricks

Velocity Filter effect example

### Chapter 7, Live Tuning Examples part 3 – 40 min

Adding big inertia to the velocity loop

Adding a bunch of drag

# Chapter 8, Live Tuning Examples part 4 – 57 min

# Tuning a position loop

Motion Magic

# Chapter 9, Quick Start Tuning Guide and Q&A - 38 min

Quick Start Tuning guide

Can you graph data during a match

How long does it take to tune a PID loop

How do you install the Stryke Force Tuning Tools

Does Stryke Force use 775s for everything

Stryke Force design process

NavX and field-oriented drive

Sentinel Interface Board

**Digital Servos** 

Vision systems – Stryke Force SteamWorks shooter

Wrap-up